

- (b) What is the design procedure of FIR filter windowing technique ?
- (c) Design a band stop half band filter to meet the following specifications :

Stopband edges :  $[2, 3] kHz$

Passband edge :  $[1, 4] kHz$

$A_p = 1 dB$ ,  $A_s = 50 dB$  use Kaiser and Hamming windows.

5 Attempt any two of the following :  $10 \times 2 = 20$

- (a) Discuss the features and applications of Goertzel algorithm. How DFT can be implemented with convolution.
- (b) Explain the term Discrete Convolution and analyze it with proper example. Also illustrate Convolution properties.
- (c) How the spectral analysis of non-stationary signals is achieved using Hamming window. What is periodogram Analysis and discuss its applications.



(Following Paper ID and Roll No. to be filled in your Answer Book)

**PAPER ID : 0300**

Roll No.

B. Tech.

(SEM. VII) EXAMINATION, 2008-09  
FUNDAMENTAL OF DIGITAL SIGNAL PROCESSING

Time : 3 Hours]

[Total Marks : 100

- Note : (1) Attempt all questions.  
(2) Each question carries equal marks.  
(3) Be precise to your answers.

1 Attempt any four of the following :  $5 \times 4 = 20$

- (a) Consider time domain representation of discrete time signals and explain the importance of length and size of the signals in the mathematical representation.

- (b) Let  $x[n] = \{1, 2, 0, 0, 4\}$  find its energy and average power.

- (c) Let  $x[n] = \{1, 2, 5, -1\}$ . Generate  $x[2n]$

and various interpolated version of  $x \uparrow [n/3]$ .



(d) In a discrete time system discuss Accumulator and moving average filter.

(e) Explain the term DFT and IDFT. Find DFT of

$$x(n) = \{2, -1, 4, 3\}$$

(f) Illustrate properties of DFT.

2 Attempt any **four** of the following : 5×4=20

(a) How discrete time signals are generated from continuous time signals. Let  $g_a(t)$  be a continuous time signal and the sequence  $g[n] = g_a(nT)$  for  $-\infty < n < \infty$  with  $T$  as sampling frequency of the sampling is done by

$$p(t) = \sum_{-\infty}^{\infty} \delta(t - nT) \text{ such that}$$

$$g_p(t) = g_a(t) p(t)$$

prove that  $G_p(\Omega) = \sum_{n=-\infty}^{\infty} g_a(nT) e^{-j\Omega nT}$

(b) Explain and compare discrete time processing of continuous time signal and continuous time processing of discrete time signals.

(c) Let  $x[n] = \{-1, 2, 3, 2\}$ ,  $t_s = 1$ . What is the value of the reconstructed signal  $x(t)$  at 2.5s that results from step and linear interpolation.

(d) With block diagram explain Digital Processing of Analog signals.

(e) What makes a difference Equation ; LTI or Non-linear or time varying.

(f) Find the impulse response of

$$y[n] - 0.6y[n-1] = 4x[n] \text{ and}$$

$$y[n] - 0.6y[n-1] = 3x[n+1] - x[n].$$

3 Attempt any **two** parts of the following : 10×2=20

(a) Classify and discuss transfer function based on Magnitude characteristics and phase characteristics.

(b) Discuss basic structures of IIR systems for direct and cascade form.

(c) Does  $H(z) = 1 + 2z^{-1} + 2z^{-2} + z^{-3}$  describe a linear phase filters ? Explain how FIR comb filters work. What are the effects of round off noise in digital filters ?

4 Attempt any **two** of the following : 10×2=20

(a) Design Discrete-Time IIR filter from continuous time filters. Convert the analog filter

$$H(s) = \frac{1}{s+1}, \text{ with a cut-off frequency of}$$

1 rad/s to a digital filter with a cut-off frequency of  $f_c = 10 \text{ Hz}$  and  $s = 60 \text{ Hz}$ , using impulse in variance and gain matching.

